

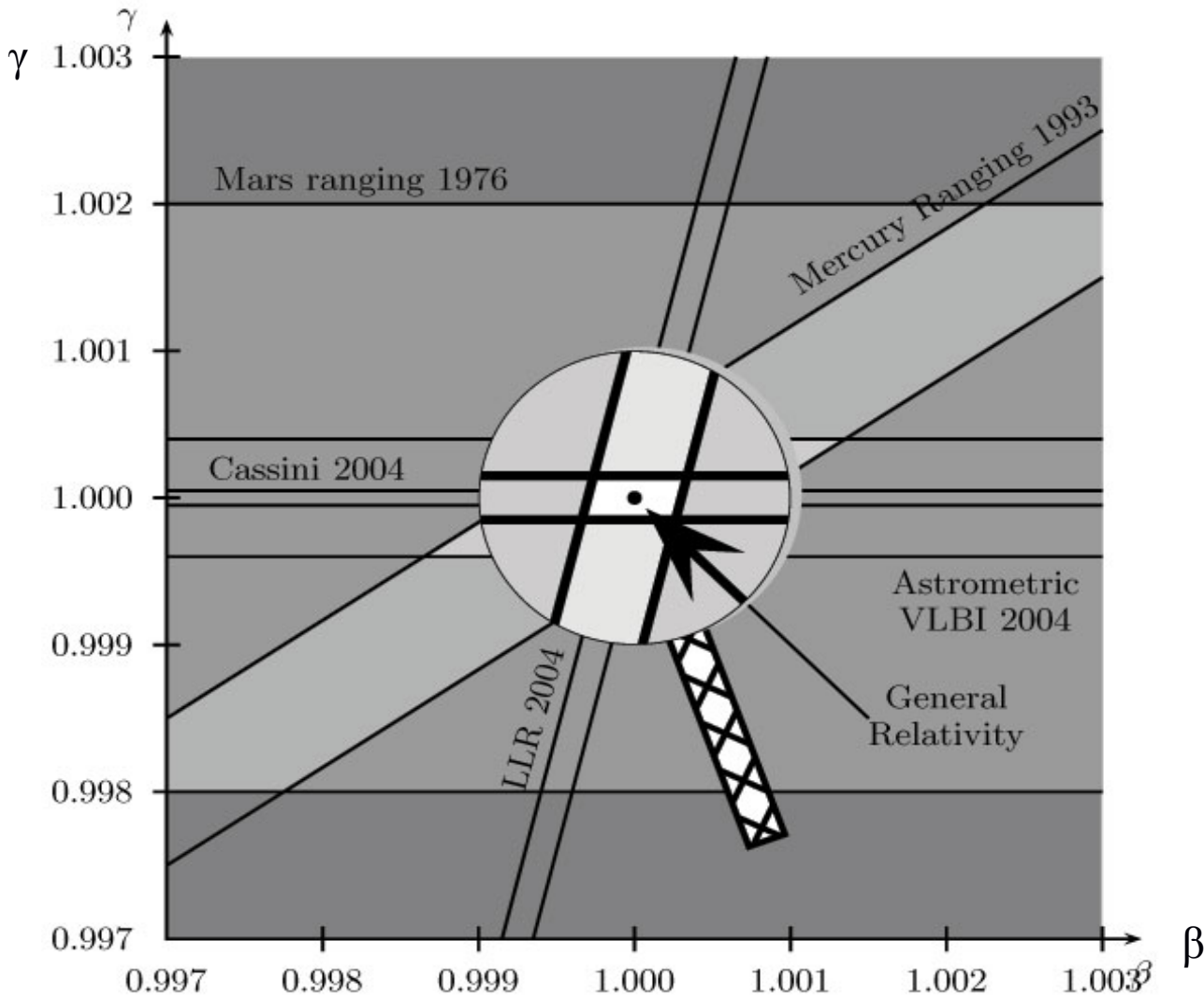
Fundamental Physics in the Framework of DLR's Research and Technology Programme

Hansjörg Dittus
German Aerospace Center (DLR)

Knowledge for Tomorrow



Precision of GR-proofs by space experiments

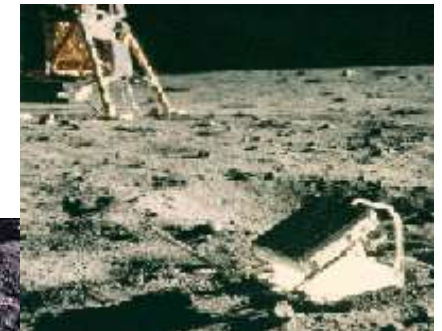
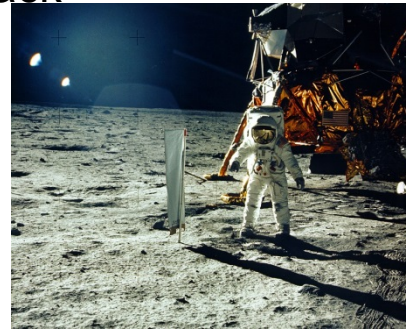
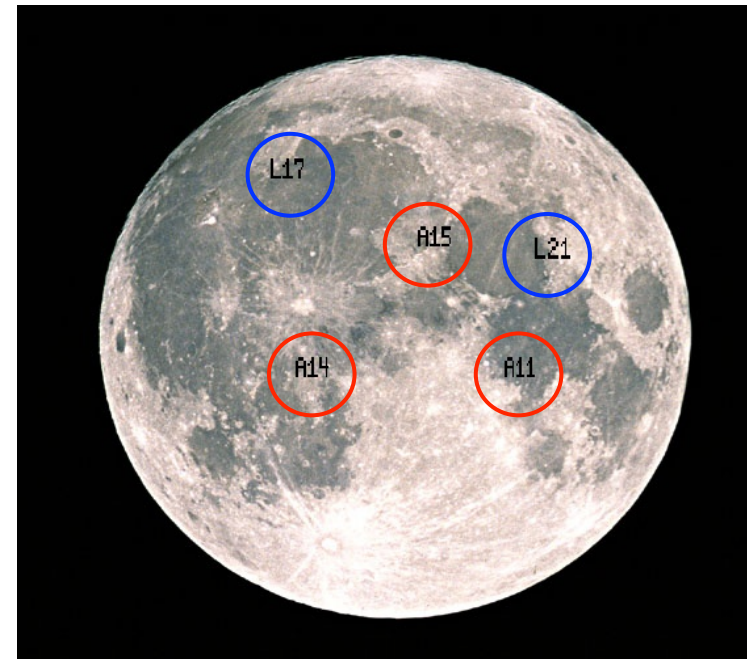


Courtesy: S. Turyshev



Lunar Laser Ranging

- since 1969 (Apollo 11, 14, 15 and Luna 17, 21)
Laser-Ranging with retro-refelctors on Moon surface
- Light pulses of about 200 ps with repetition rates of 0.1 s
- Beam „illuminates“ a circle of \varnothing 20 km on Moon surface
- Out of 10^{20} photons 1one coming back can be identified on Earth (ca. 1 per second)
- Accuracy: 3 cm
- Telescopes:: McDonald Obs., Fort Davis TX, Mt. Haleakala, Hawaii and OCA, Grasse



Cassini-Exp. / Shapiro Time Delay

Einstein-Infeld-Hoffmann equation

- Numerical models based on isotropic PPN n-body metric
- Planets and asteroids treated as point masses
- Accelerations calculated wrt their barycentric position

$$\ddot{\vec{r}}_i = \sum_{j \neq i} \frac{Gm_j (\vec{r}_j - \vec{r}_i)}{|\vec{r}_j - \vec{r}_i|^3} \cdot \left[1 - \frac{2(\beta + \gamma)}{c^2} \sum_{k \neq i} \frac{Gm_k}{|\vec{r}_i - \vec{r}_k|} - \frac{2\beta - 1}{c^2} \sum_{k \neq j} \frac{Gm_k}{|\vec{r}_j - \vec{r}_k|} + \gamma \frac{|\dot{\vec{r}}_i|^2}{c^2} + (1 + \gamma) \frac{|\dot{\vec{r}}_j|^2}{c^2} - \frac{2 + 2\gamma}{c^2} \dot{\vec{r}}_i \cdot \dot{\vec{r}}_j - \frac{3}{2c^2} \left(\frac{(\vec{r}_i - \vec{r}_j) \cdot \dot{\vec{r}}_j}{|\vec{r}_j - \vec{r}_i|} \right)^2 + \frac{1}{c^2} (\vec{r}_j - \vec{r}_i) \cdot \ddot{\vec{r}}_j \right] + \frac{1}{c^2} \sum_{j \neq i} \frac{Gm_j}{|\vec{r}_j - \vec{r}_i|^3} ((\vec{r}_j - \vec{r}_i) \cdot ((2 + 2\gamma)\dot{\vec{r}}_i - (1 + 2\gamma)\dot{\vec{r}}_j)) + \frac{3 + 4\gamma}{2c^2} \sum_{j \neq i} \frac{Gm_j}{|\vec{r}_j - \vec{r}_i|}$$



Time delay for curved space-time due to grav. fields of Sun and Earth

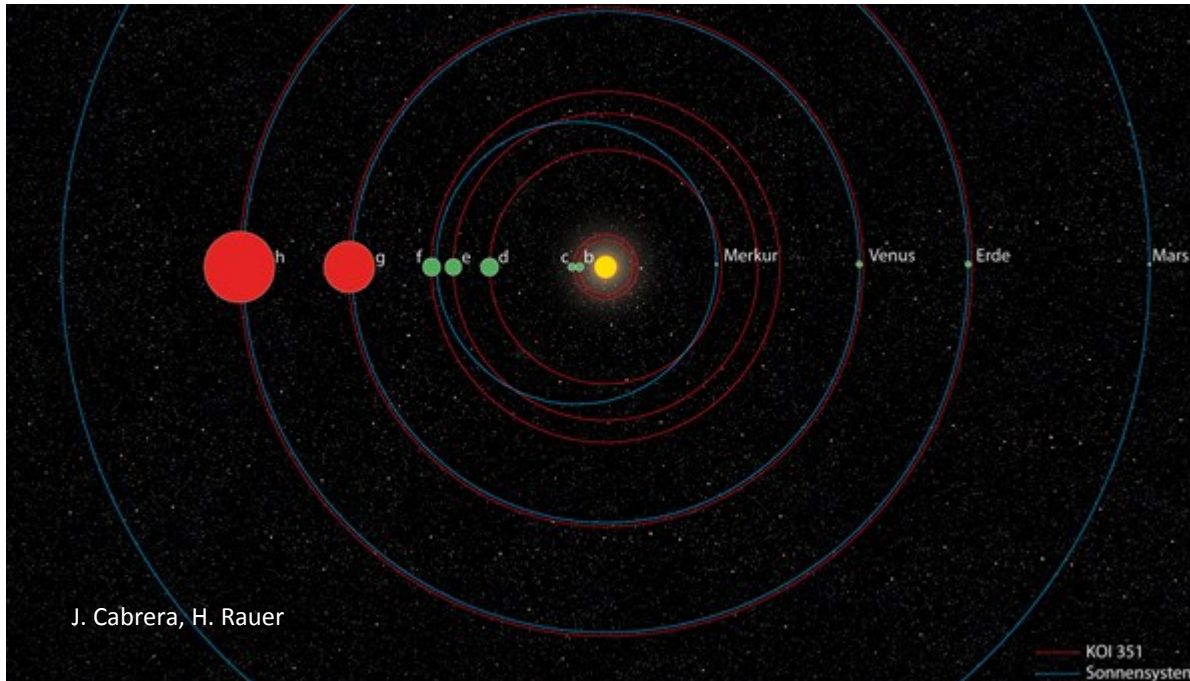
$$\Delta t = \frac{|\vec{r}_t^C - \vec{r}_s^C|}{c} + \frac{(1 + \gamma)Gm_S}{c^3} \ln \left(\frac{r_s^S + r_t^S + |\vec{r}_t^S - \vec{r}_s^S| + (1 + \gamma)Gm_S / c^2}{r_s^S + r_t^S - |\vec{r}_t^S - \vec{r}_s^S| + (1 + \gamma)Gm_S / c^2} \right) + \frac{(1 + \gamma)Gm_E}{c^3} \ln \left(\frac{r_s^E + r_t^E + |\vec{r}_t^E - \vec{r}_s^E|}{r_s^E + r_t^E - |\vec{r}_t^E - \vec{r}_s^E|} \right)$$

Cassini Conjunction Experiment 2002:

- Satellit - Earth distance > 10⁹ km
- Ranging: X~7.14GHz & Ka~34.1GHz (dual band)
- Result: $\gamma = 1 + (2.1 \pm 2.3) \cdot 10^{-5}$



The Planet System KOI-351, detected in 2013

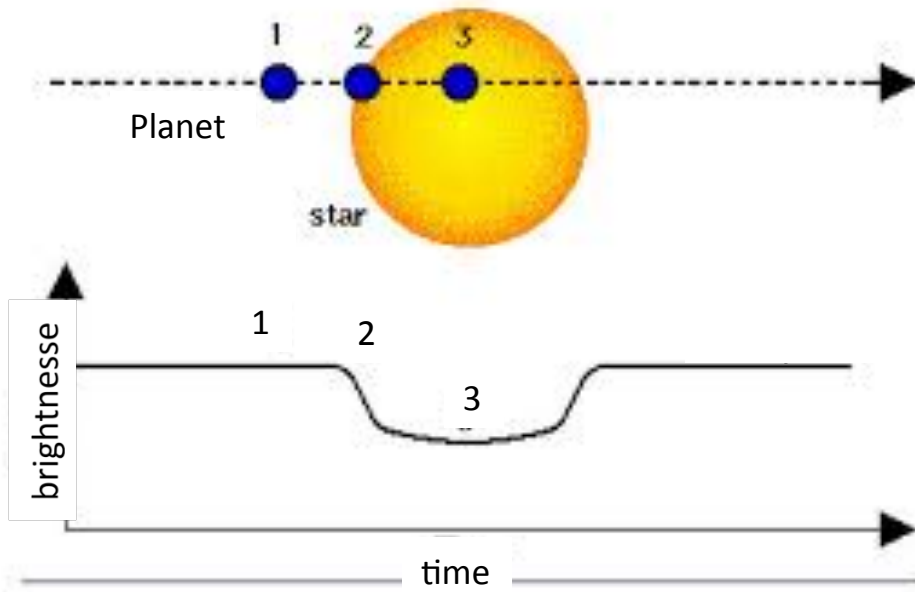


- 2500 light years far distant from sun
- main row star in the Milky Way
- 7 planets on a distance of only 1 AU
- detected with Kepler S/C by transition method between 2008 and 2013

How stable is the system?



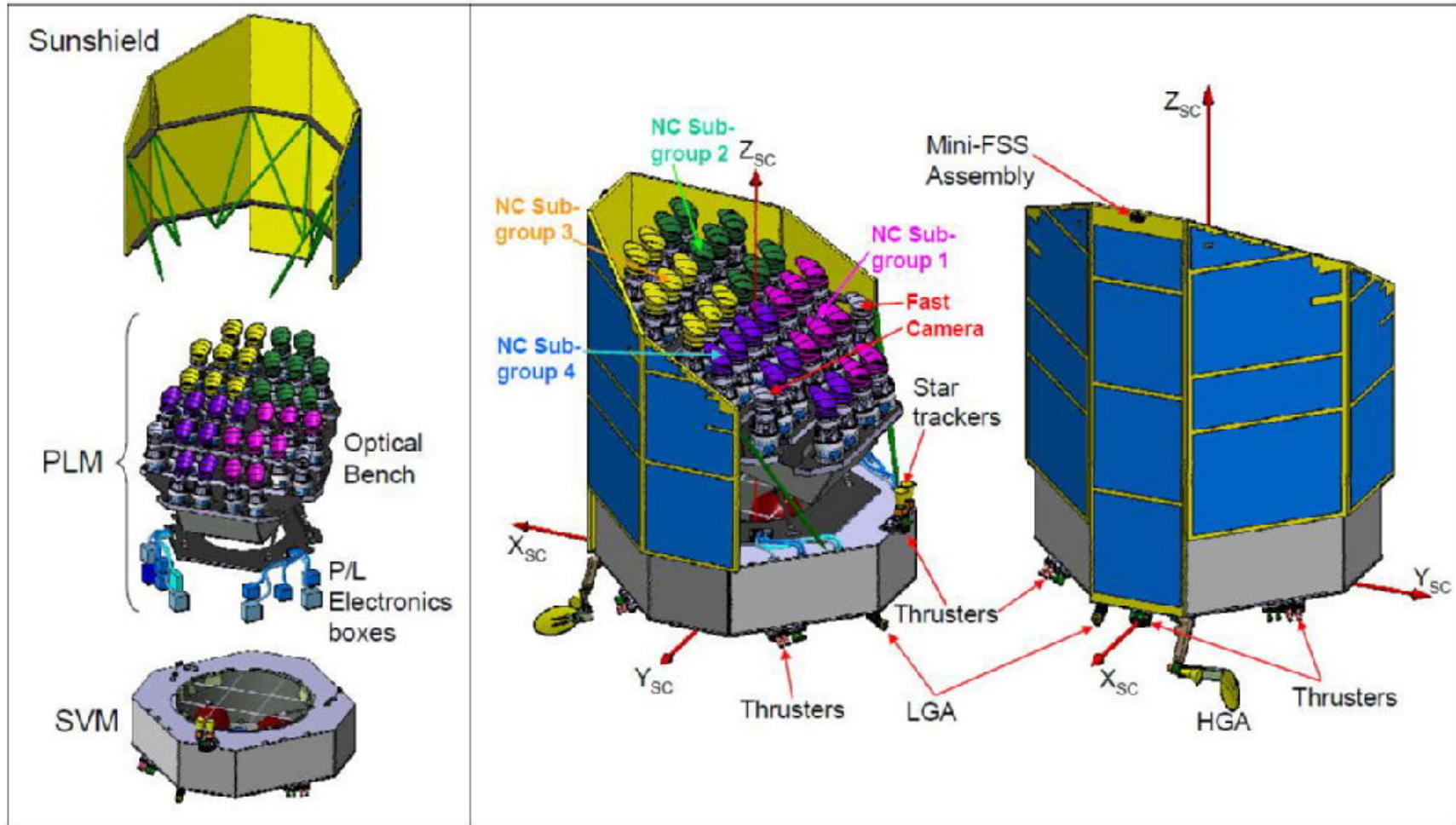
The Transition Method



Venus transition
at sun on 6.6.2012



PLATO S/C



Galileo S/C: A chance for Fundamental Physics?

- 2 L3 FOC satellites launched on 22/08/2014

in:

Elliptical orbit with deviation from nominal orbit of -9.500km up to +2.700km

Eccentricity 0.23

Speed Apogee $\sim 3\text{km/s}$ and Perigee $\sim 5\text{km/s}$

Delta Inclination of 6 degrees with respect to nominal plane

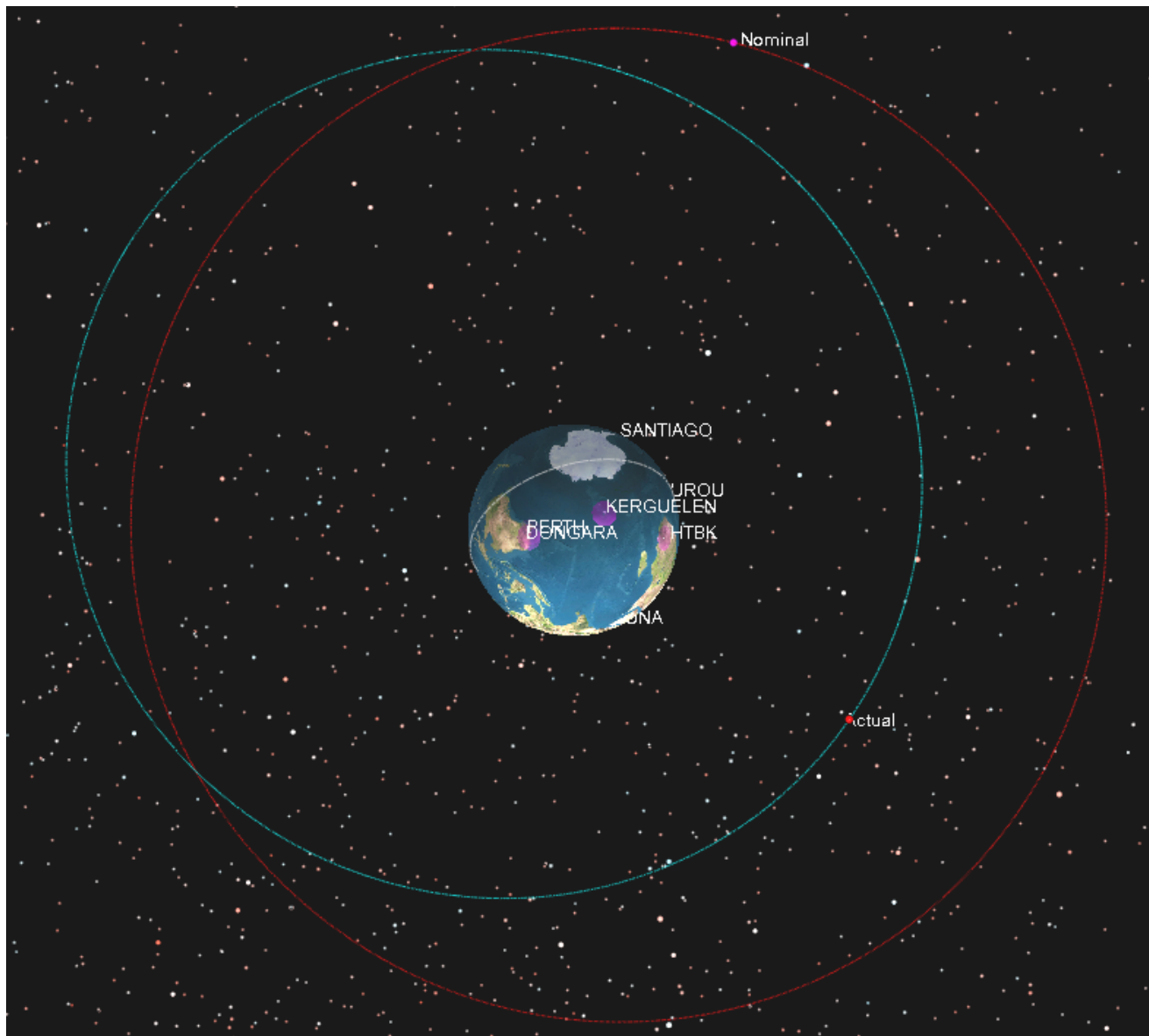
Orbit has been changed because Earth sensors are not reliable for these altitudes -> gyros might become mandatory input for AOCS (gyro spec to be checked)

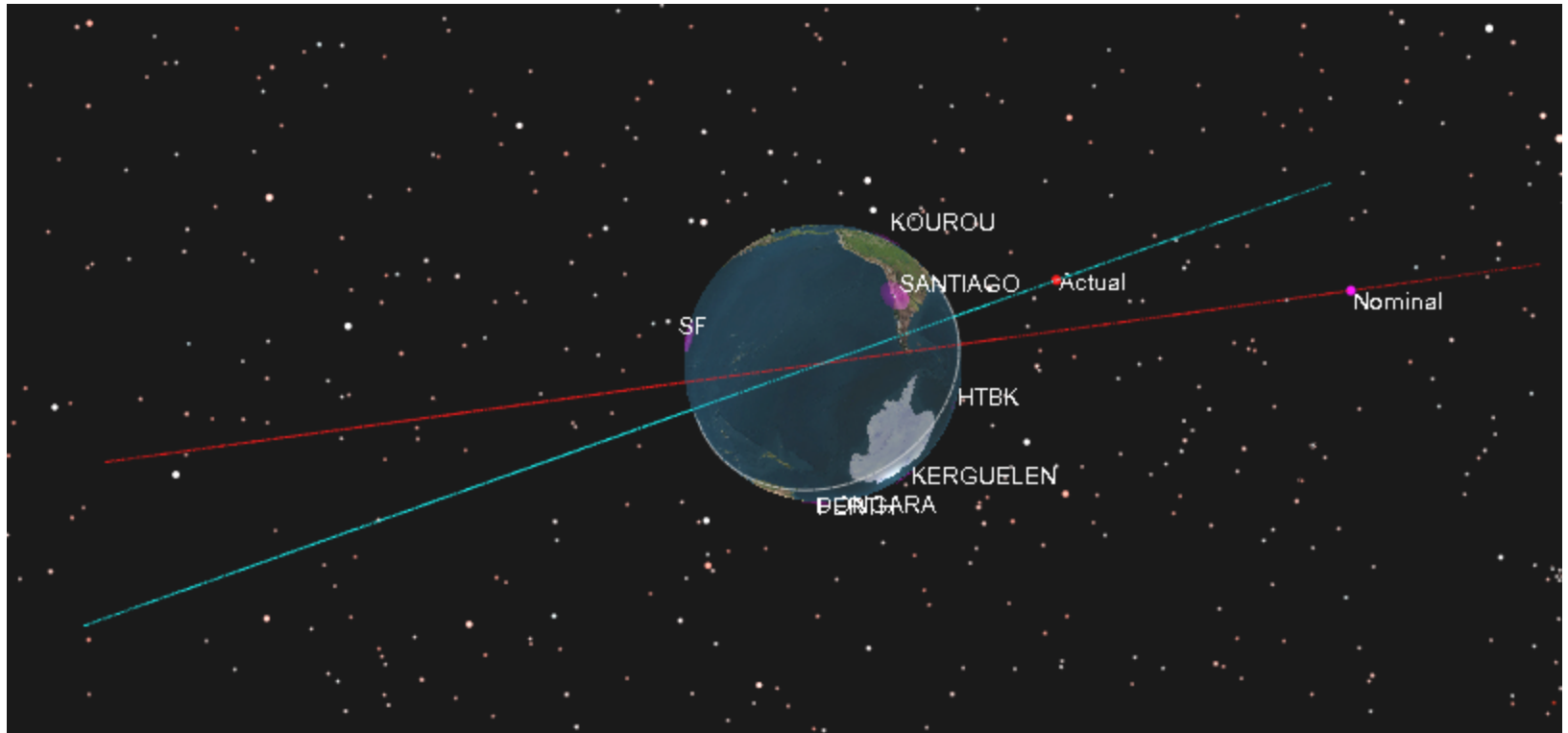
Yaw steering (clocks never pointing to the sun) coincidence at Perigee could exceed the tolerance



Image courtesy of: ESA / ZIGZAG-DR







What could be done with 2 GNSS satellites which failed their orbit?

- Clock stability: 10^{-15} per orbit
- Grav. Redshift test improvement: 10^2
- Perihelion shift: 10^1
- Alternative theory tests
- Yukawa potential at length scale 104 m: 10^5



New Target Orbit for GSat 201

Orbit insertion: 5.11.2014

Perigee (km)	13,728.7	to	17,340.8
Apogee (km)	25,922.1	to	25,858.8
Height diff. (km)	12,193.4	to	8,518.0
Excentricity	0.2326	to	0.1522



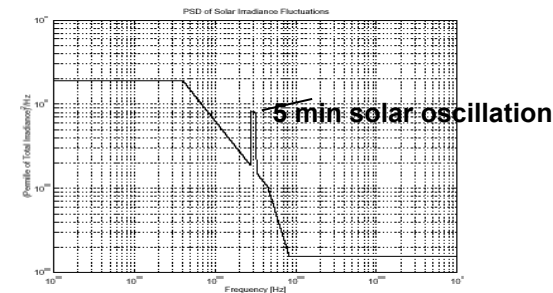
Observation Tools

- Satellites and orbital platforms
 - Observations from Satellites (e.g. astronomical and astrophysical telescopes)
 - Experiments with Satellites (e.g. spacecraft tracking by Doppler shift)
 - Experiments on Satellites (e.g. GP-B)
- Needs a toolbox of highly precise sensors to measure
 - Distance (e.g. Laser Ranging, Doppler shift, optical transponders)
 - Time (e.g. cavity clocks / frequency standards, atomic / optical clocks, freq. combs)
 - Acceleration (SQUID-based sensing, gyroscopes, inertial sensors)
 - Angles (pointing, star sensors, VLBI)
- Needs reliable and precisely operating actuators
 - Thrusters
 - Reaction wheels
 - Piezo-techniques for mirror pointing



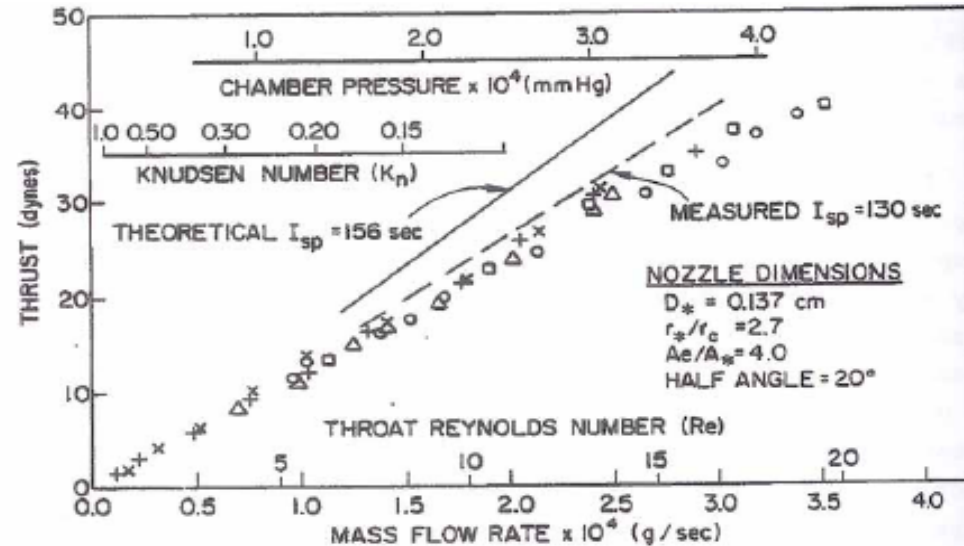
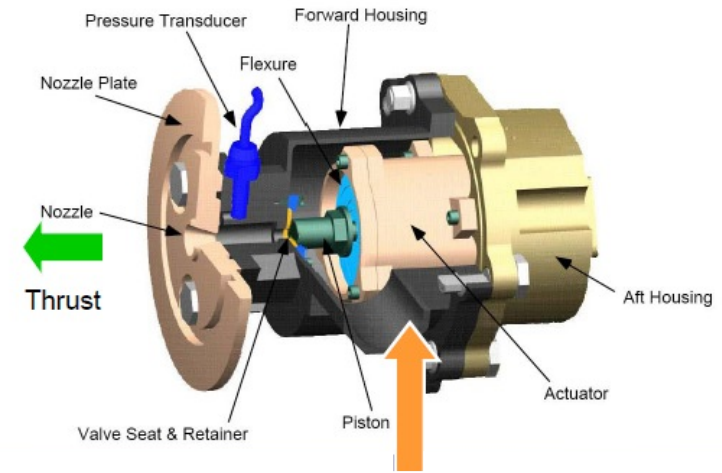
Drag-free Thrust Control

- mN/ μ N-Thrusters:
 - for compensation of forces deviating the satellite on its ideal free fall orbit (geodesic)
 - for compensating of tidal forces and satellite dynamics in formation flight
- Disturbance forces
 - atmospheric drag:
forces: ca. 1mN; moments: 10 μ N · m
 - radiation pressure by Earth albedo:
forces: ca. 10 μ N; moments: 1 μ N · m
 - magnetic moments by s/c interaction with the Earth magnetic field (typically):
moments: 100 μ N · m, after moment compensation: 10 μ N · m
 - solarer radiation pressure:
forces: ca. 10 μ N, moments: 0.1 μ N · m
- Thrust requirements
 - **thrust control: $\Delta S < \pm 0.1 \mu$ N**
 - **residual acceleration: $< 10^{-15} \text{ m}/(\text{s}^2 \cdot \text{Hz}^{0.5})$**
 - **permanent operation**



- Gas-proportional thruster on Gravity Probe B

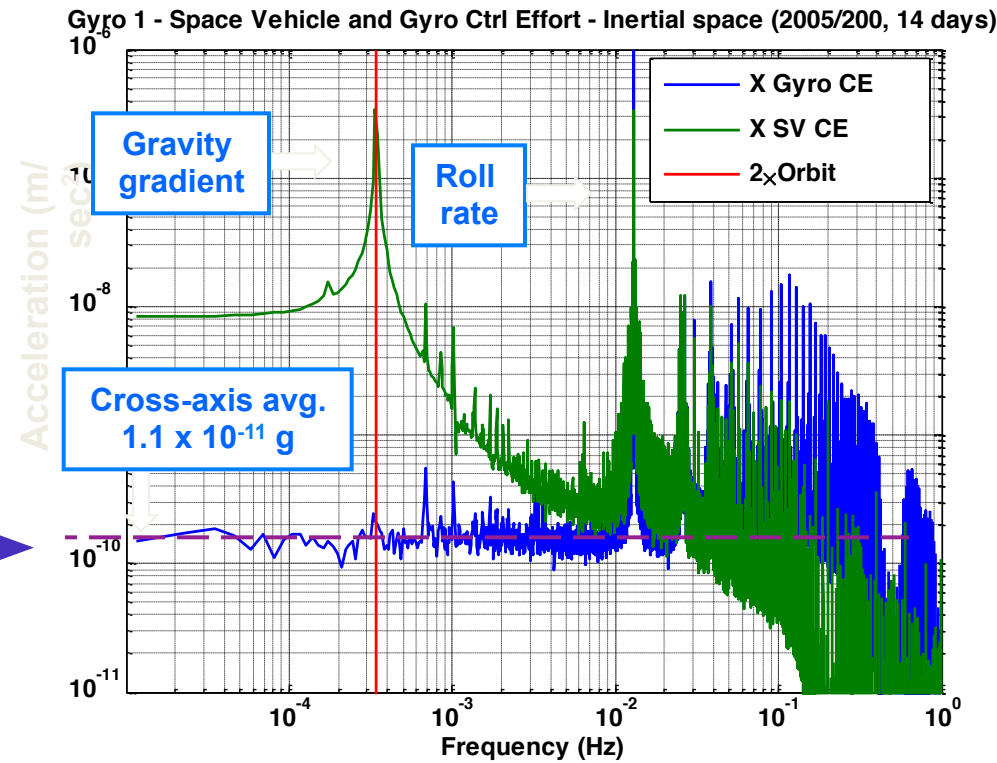
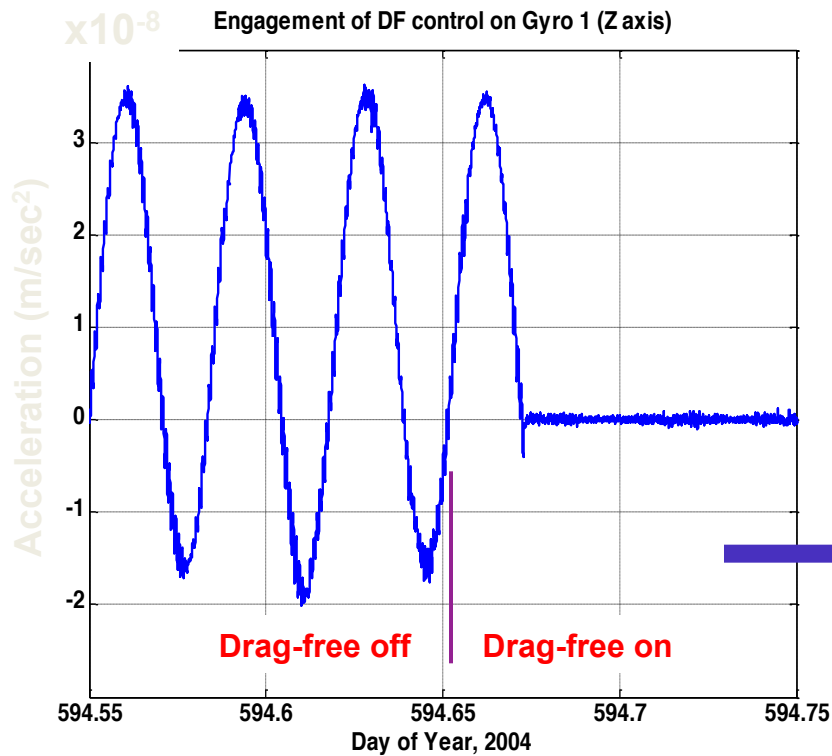
- Set of $4 \times 4 = 16$ proportional thrusters, fuel: He (boil-off gas from 2.3 m³ Dewar) at 670 to 2,330 Pa
- $S < 10$ mN for 6 DOF
- $I_{sp} = 130$ s
- mass flux: 6.5 mg / s
- noise: 25 $\mu\text{N} \cdot \text{Hz}^{-0,5}$



Source: Stanford University



• Drag-free performance of GP-B

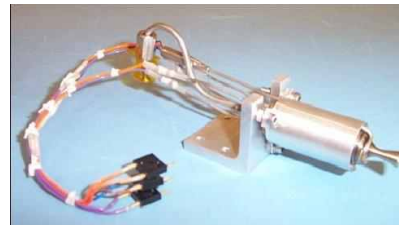
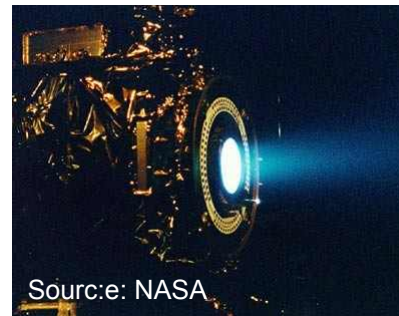
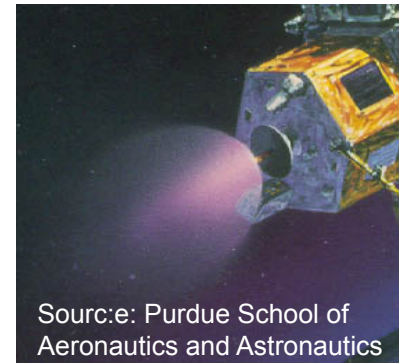


F. Everitt et al.



Satellite Thrusters

- Huge dynamic range
 - $\sim \mu\text{N} < S < 40 \text{ kN}$; $200 \text{ s} < I_{sp} < 3,000 \text{ s}$
- Extremely low thrust systems
 - Arcjet Engines:
Hybrid systems for continuous or pulsed thrust
light arc ignition of gases
 $100 \text{ mN} < S < 1\text{N}$; $500 \text{ s} < I_{sp} < 2,000 \text{ s}$
 - Ion-thrusters (Hall thruster):
non-chemical systems for continuous thrust over long time
ionising of a Xenon atom beam
 $2 \text{ kW} < P < 50 \text{ kW}$
 $40 \text{ mN} < S < 7200 \text{ mN}$; $3,000 \text{ s} < I_{sp} < 9,000 \text{ s}$
 - Magneto-plasma dynamical thrusters:
beam acceleration by EM-fields
 S up to 100 N ; $I_{sp} \approx 5,000 \text{ s}$
 - Cold gas thruster:
inert gas (typically N_2) exhaust
 $1\text{mN} < S < 10 \text{ N}$; $50 \text{ s} < I_{sp} < 80$
- Micropropulsion systems:
 - Typically Fundamental Science Mission (e.g. LISA) need μN – thrust w
sub μN – precision control



Micropropulsion Systems

- **MEMS-based propulsion**

- Main incitement and motivation: development of thrust systems for nano-satellites
- Microfabricated: Liquid Micro-Thruster, Micro-Ion Engine, ...

Requirements:

Thrust level 1–1000 N

Impulse bit 1–100 N s

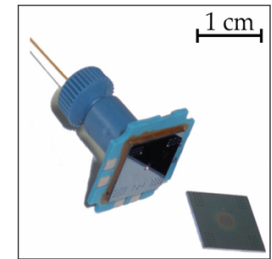
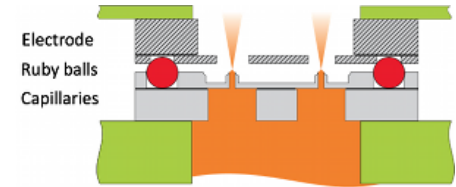
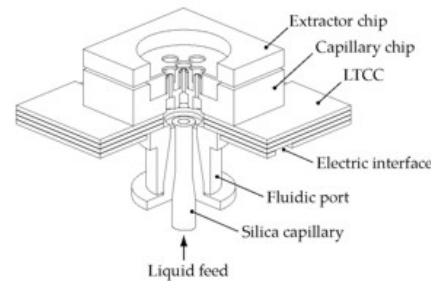
Specific impulse 160 s

Mass <0.1 kg

Power consumption <1 W

Volume <1 cm³

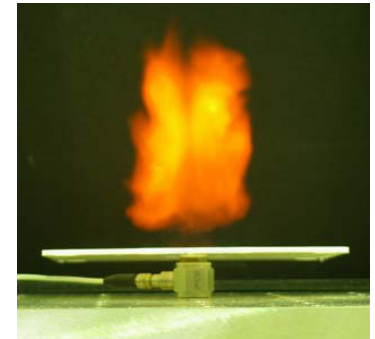
Operating temperature <1700 K



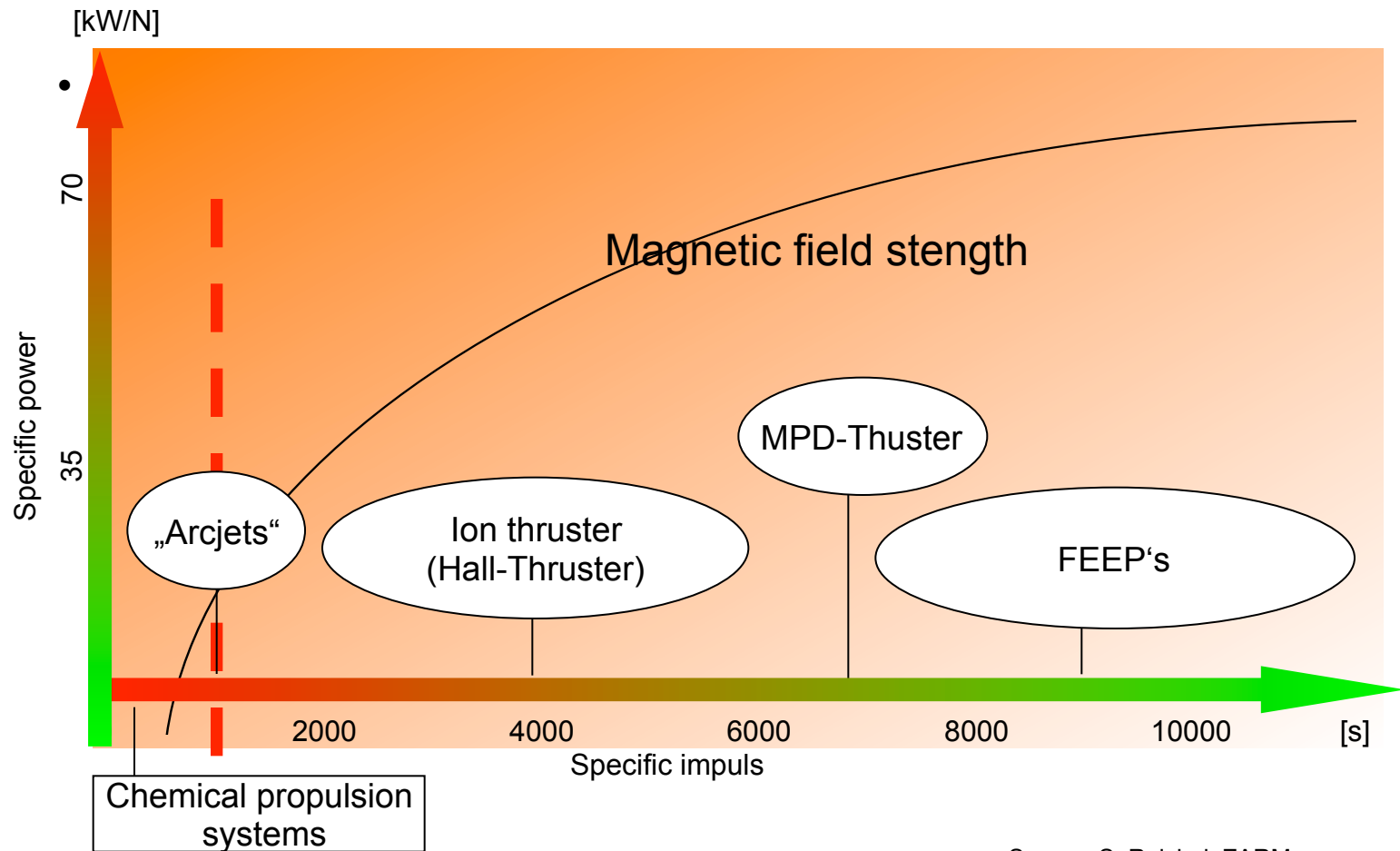
Sourc:e: École Polytech. d. Lausanne

- **Laser induced ablative thrusters**

- *S. Karg*, DLR-TP
- New concept for low thrust propulsion



Micropropulsion Systems

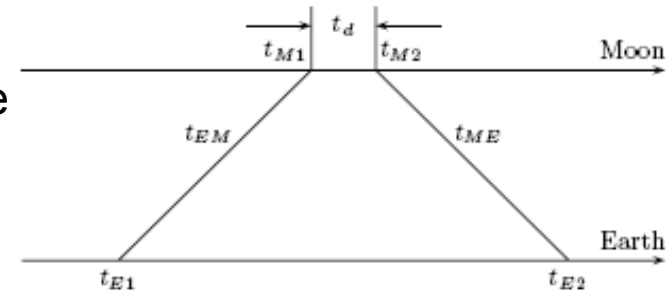


Source: S. Reichel, ZARM



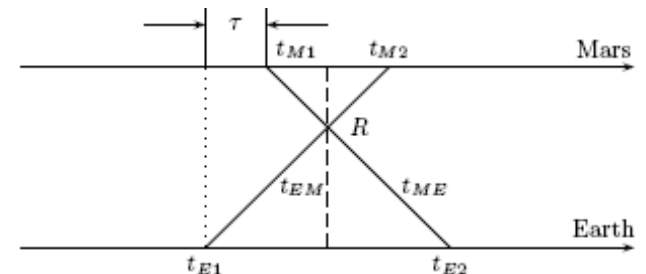
Optical links and Laser ranging

- Optical transponders (on-board lasers, telescopes, timing receiver)
- Demonstrated over 0.17 AU (24 million km) with Messenger S/C and Mars Global Surveyor S/C (1-way, 80 million km)
- Nd:YAG laser, pulse rate 8 Hz
- Needs atmospheric correction: calibration can be done by ranging to near earth objects (e.g. LAGEOS) from different stations



Echo transponder for e.g. lunar laser ranging
Time delay must be known

	Messenger S/C	MOLA on Mars Global Surveyor S/C (1-way only)
range	$2.4 \cdot 10^7$ km	$8 \cdot 10^7$ km
pulse width	10 ns (up), 6 ns (down)	5 ns
pulse energy	16 mJ (up), 20 mJ (down)	150 mJ
repetition rate	240 Hz (up), 8 Hz (down)	56 Hz
laser power	3.84 W (up), 0.16 W (down)	8.4 W
beam divergence	60 μ rad (up), 100 μ rad (down)	50 μ rad
receive area	0.042 m ² (up), 1.003 m ² (down)	0.196 m ²



Asynchronous transponder for satellite laser ranging
Repetition rate must be known

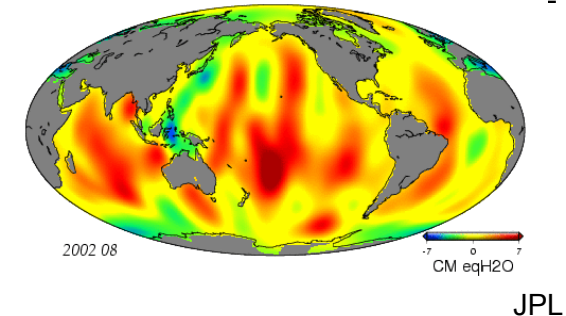
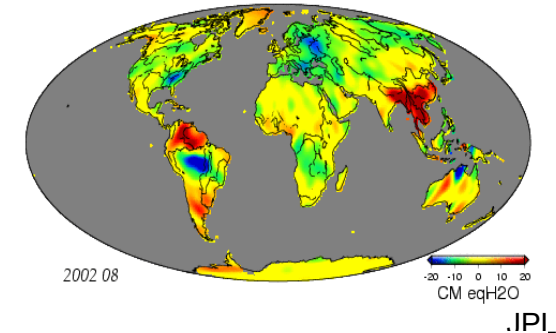
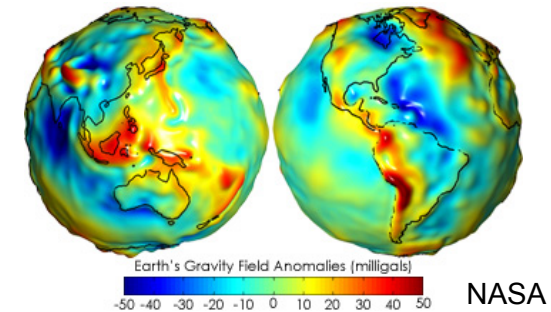
John J. Degnan, in Lasers, Clocks, and Drag Free



GRACE

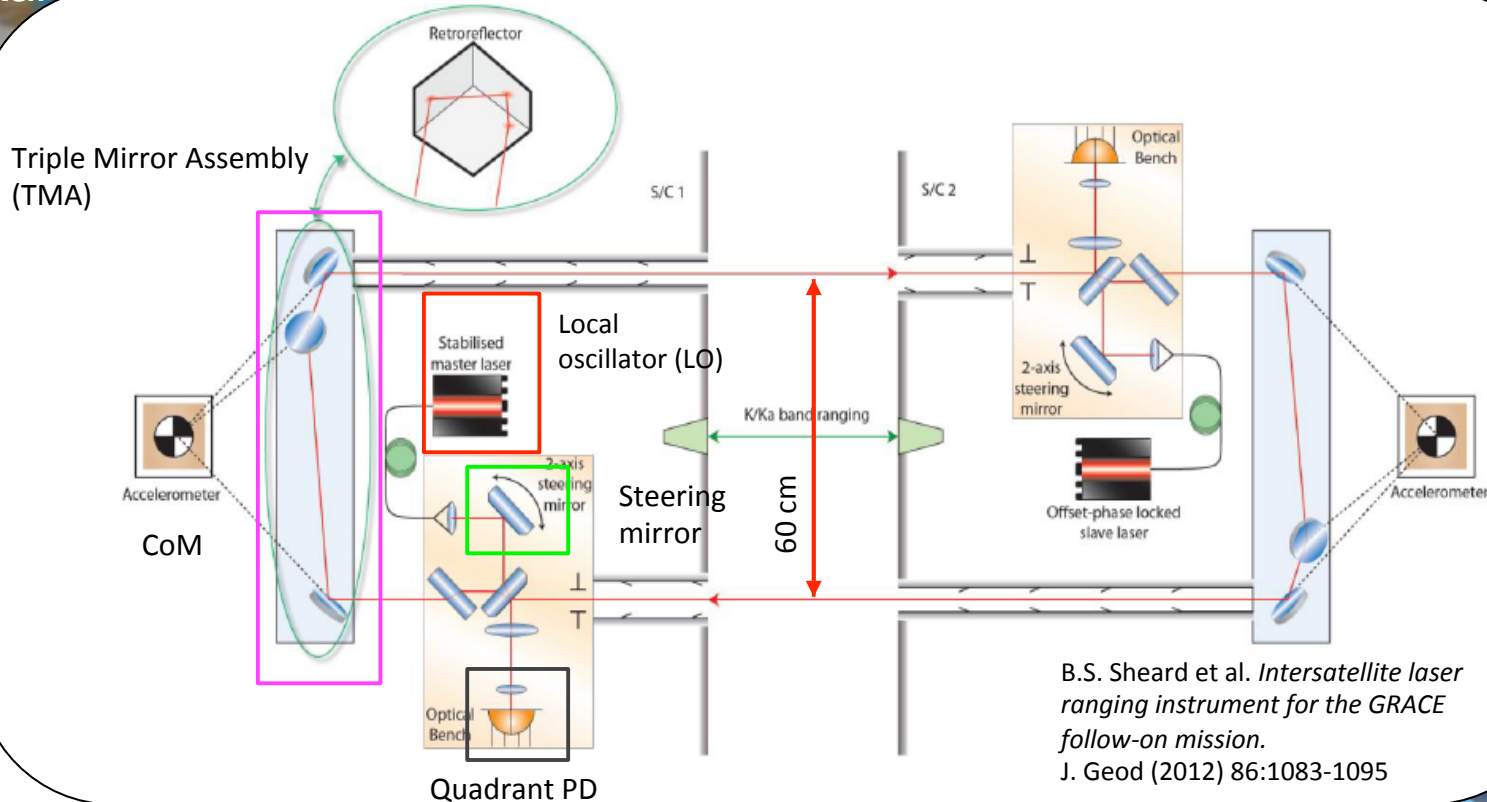
(Gravity Recovery And Climate Experiment)

- Joint NASA/German Aerospace Center mission
- Aims to continuously measure Earth's gravity field
- Pair of S/C around Earth, 220km distance along orbit
- The distance between the S/C varies depending on the Earth mass distribution
- Distance measurement by a two-way **microwave-ranging link** (accuracy in the μm range)
- Polar Orbit 500km above Earth
- Input to
 - Oceanography
 - Hydrology
 - Glaciology
 - Geology
 - Climate change analysis
- End of lifetime: expected 2015 – 2016
- Follow on mission GRACE-FO will start in 2017 in order to guarantee a continuous flow of data



GRACE – Follow On

- Start: August 2017
- The basic principles of the GRACE mission do not change
- Additional second distance measurement system LRI
- LRI – Laser Ranging Instrument
- The distance accuracy will be at least a factor of 10 better than GRACE
- DLR-RY will develop the LRI by CiK to ground support

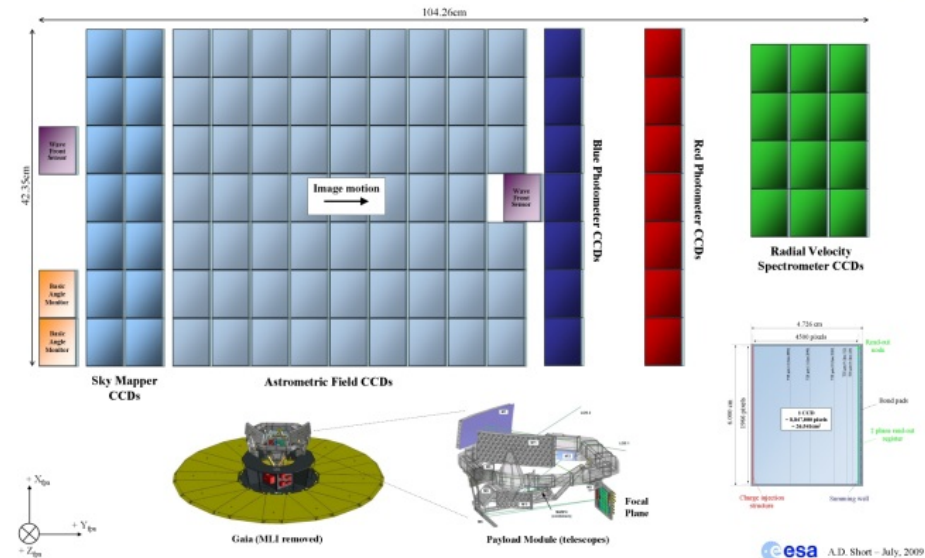


B.S. Sheard et al. *Intersatellite laser ranging instrument for the GRACE follow-on mission.*
 J. Geod (2012) 86:1083-1095

GAIA

Global Astrometric Interferometer for Astrophysics

- Launch: Dec 19, 2013
- Orbit: Lissajous-type orbit around L2
- Most precise 3D map of the Milky Way and its dynamic based on parallax determination, distance, and velocity measurements
- Determination of brightness, temperature and composition
- 2 identical telescopes and imaging systems, BP/RP (Blue and Red Photometers) and RVS (Radial-Velocity Spectrometer)
- Angle measurement: 24 mas (50 times better than Hipparcos)
- Distance measurements: up to 30,000 ly; with accuracies between 10^{-5} and 0,2



Clocks to explore space-time

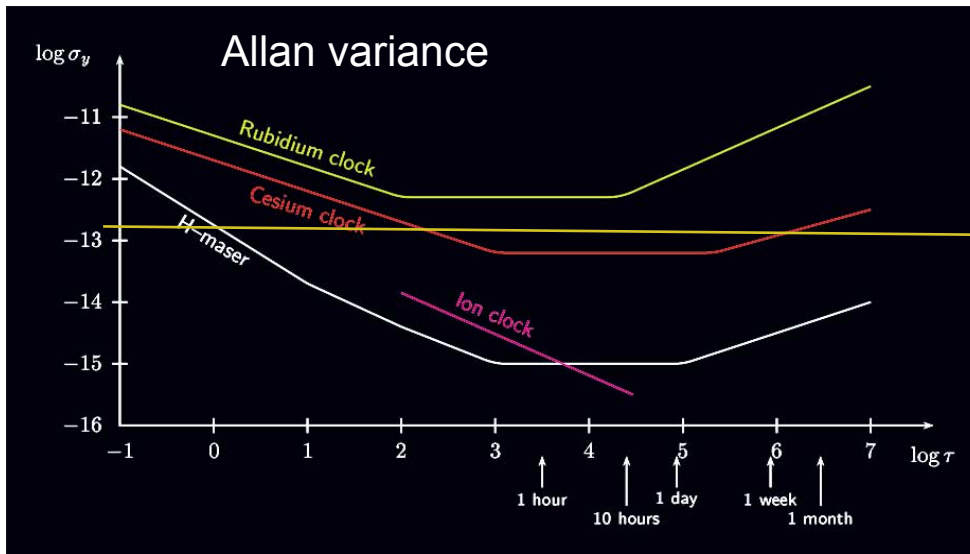
- Redundant measurements

- Measuring acceleration of S/C on geodesic via ranging and Doppler tracking
- Measuring redshift of clocks on-board S/C

for example Pioneer Anomaly

$$\frac{\Delta v}{v} = \frac{1}{c^2} \int_{20 AU}^{90 AU} a_{PA} dx \approx 10^{-13}$$

- Clock exploration does not depend on geodesic motion, independent from acceleration
- Clock exploration is cumulative
- Clocks automatically isolate the pure gravity sector
- Clocks represent an absolute DC-accelerometer



requirement for deep space missions

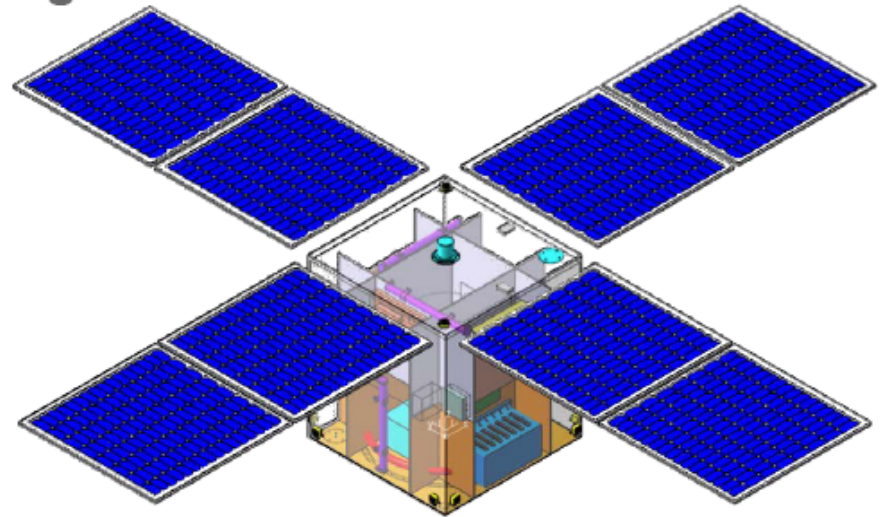
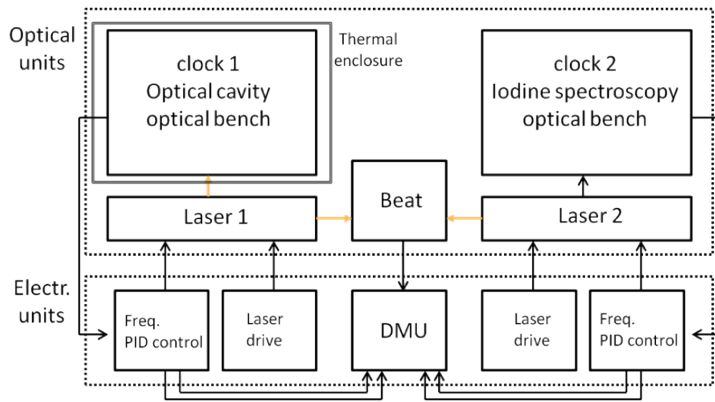
Challenge:
long term stability



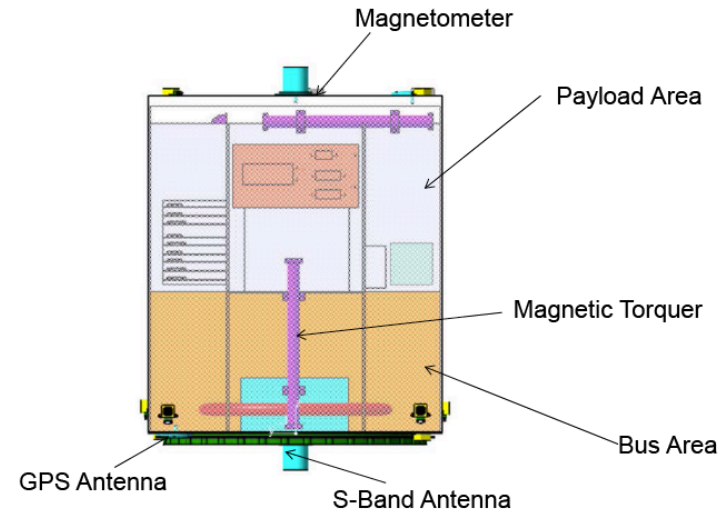
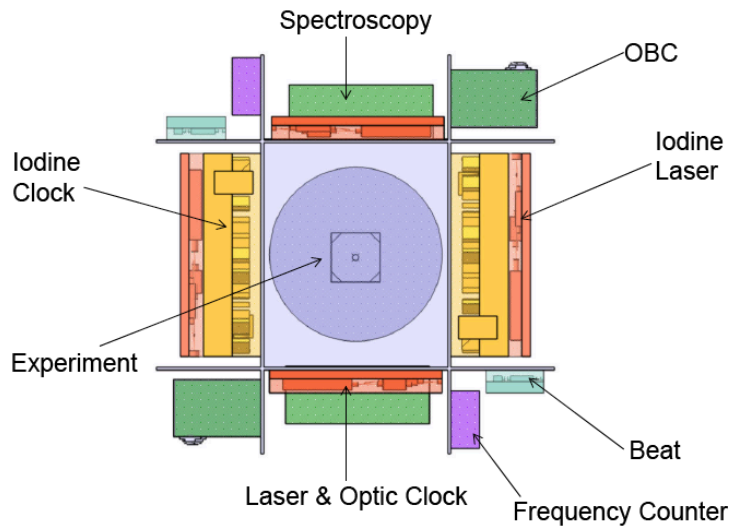
The Future



STAR / BOOST ?



270 cm



Source: STAR / BOOST collaboration

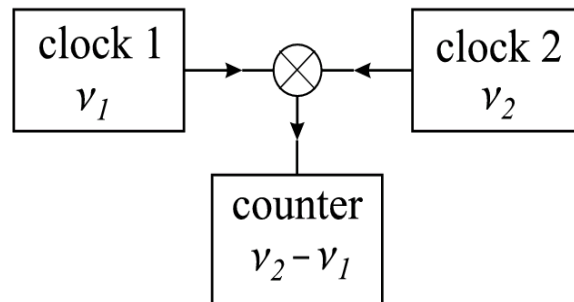


Kennedy-Thorndike experiment - Frequency comparison: BOOST (BOOst Symmetry Test)



CLOCK 1
with a dependence
on v

CLOCK 2
with a **different**
dependence on v



BEAT measures **difference in frequencies**

SATELLITE



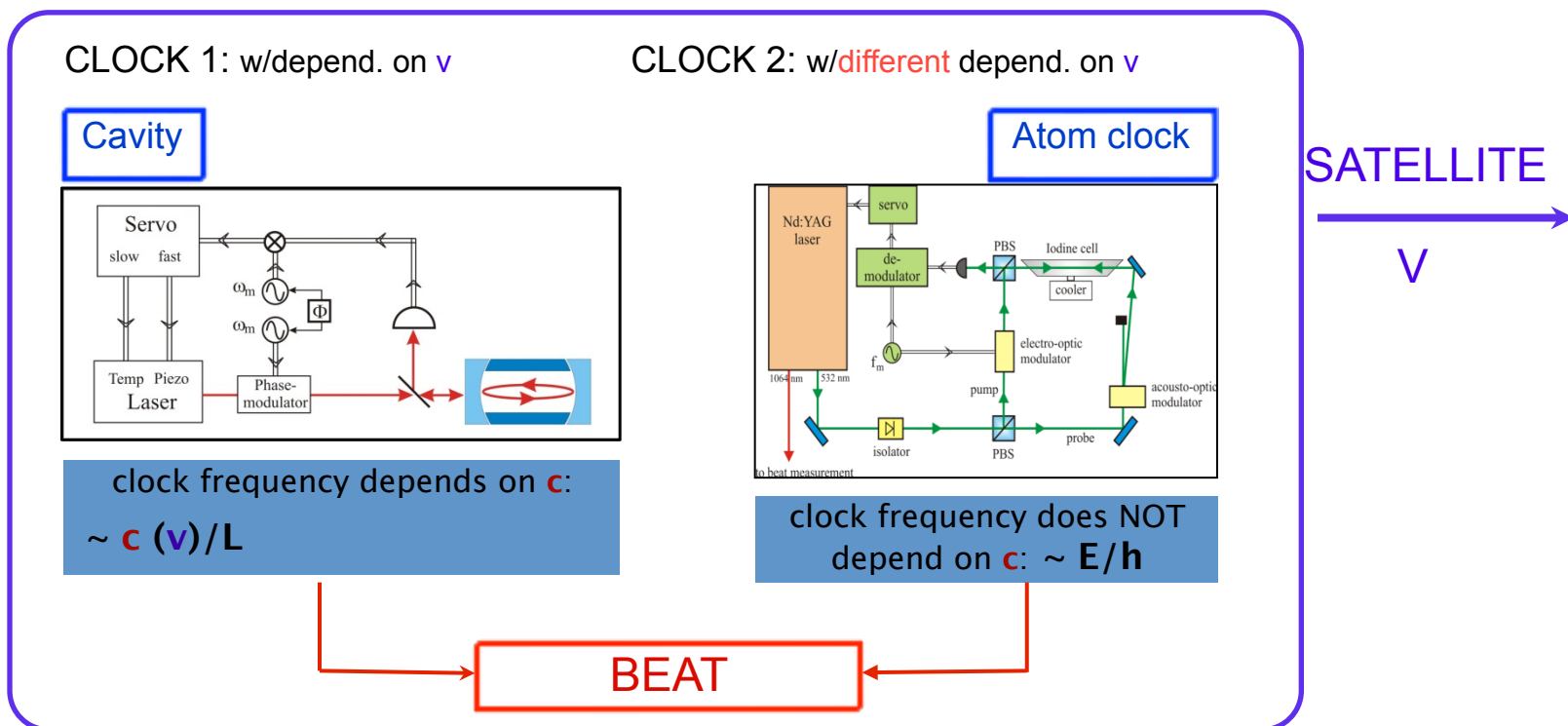
v

⇒ Large v variation
desired to enhance
the effect

Source: C. Braxmaier

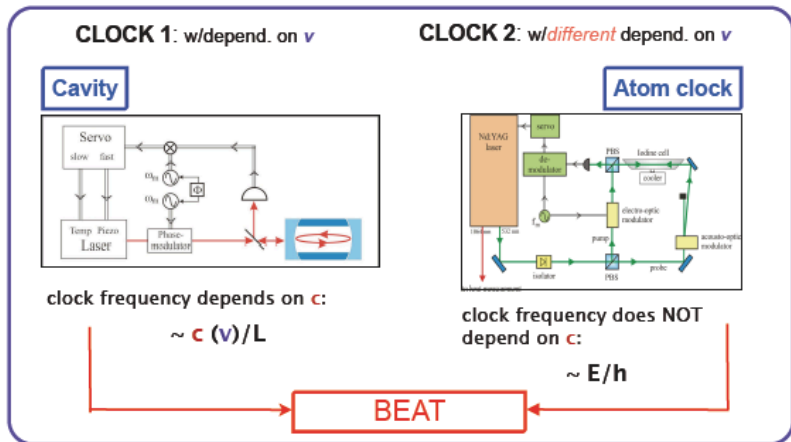
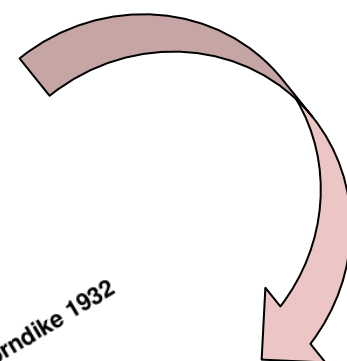


Kennedy-Thorndike experiment - Frequency comparison: BOOST (BOOst Symmetry Test)

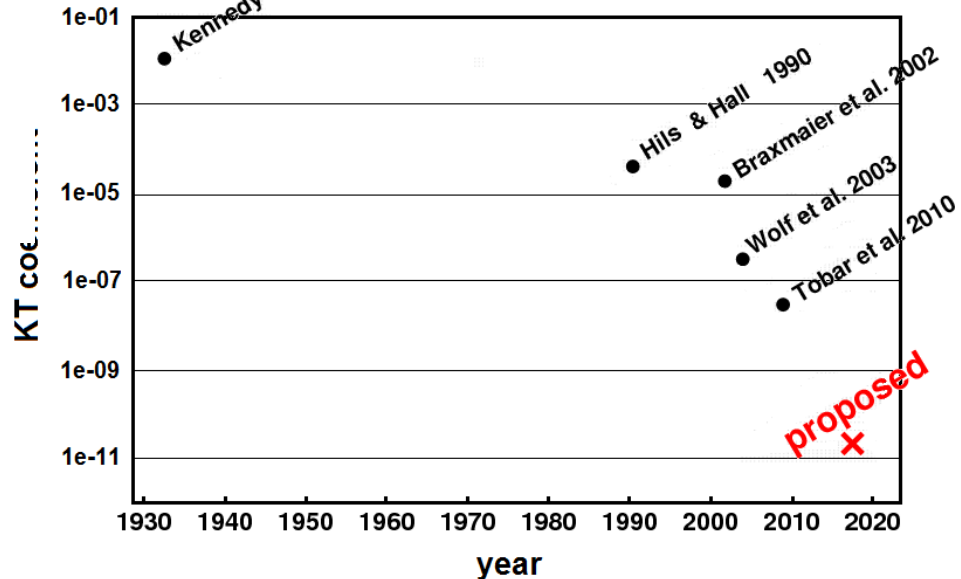


BOOST (BOOst Symmetry Test): Kennedy-Thorndike

- Testing the foundations of Special Relativity (Lorentz Boost Invariance)
 - *“Is the speed of light independent of the velocity of the Laboratory frame”*
- High velocity changes (direction) on short time scales necessary
 - **Satellite experiment:** Comparison of optical cavity and iodine clock
 - Possible **improvement:** Factor **1600**
 - SSO, 500km, 90min

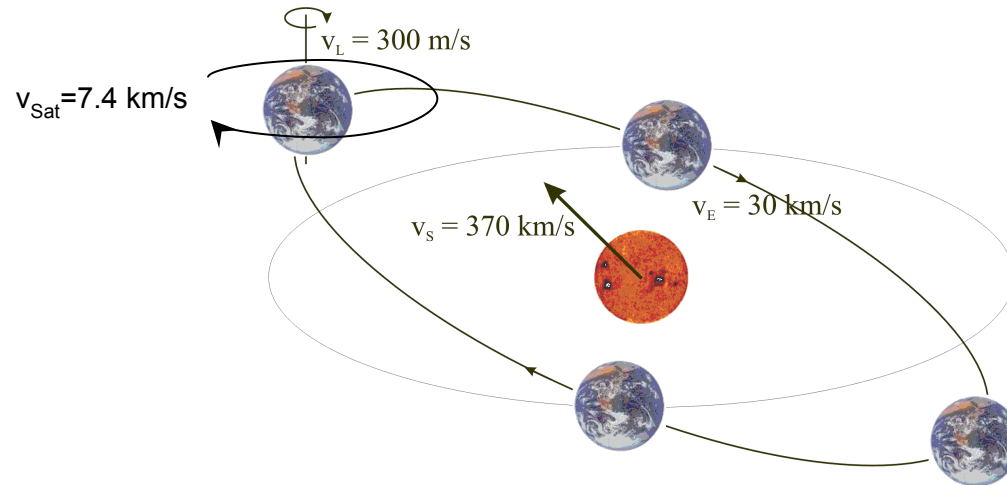


SATELLITE
V



Modulation of v - Laboratory @ satellite

Ref. frame: Cosmic Microwave Background (CMB)



Velocity of an experiment on satellite

$$\vec{v} = \vec{v}_{\text{Sol}} + \vec{v}_{\text{E}} + \vec{v}_{\text{Sat}}$$

Gain on velocity ratio

$$\frac{v_{\text{Sat}}}{v_L} = \frac{7.4 \text{ km/s}}{0.3 \text{ km/s}} = 25$$



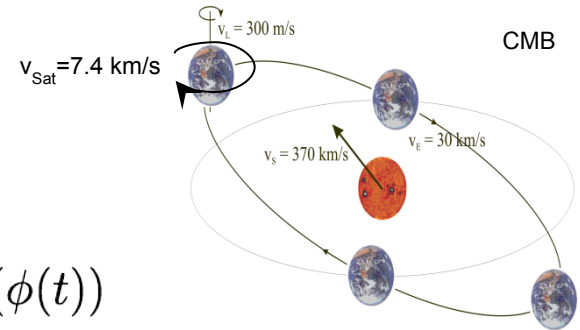
Estimation of KT-coefficient

Estimate

$$\frac{\delta_v c(v)}{c_0} = (\beta - \alpha - 1) \cdot \frac{\delta(\vec{v}^2)}{c_0^2}$$

$$\begin{aligned} \frac{\delta(\vec{v}^2)}{c_0^2} &= \frac{2\delta(\vec{v}) \times \vec{v}}{c_0^2} \simeq \frac{2|\vec{v}_{\text{Sat}}||\vec{v}_{\text{Sol}} + \vec{v}_{\text{Earth}}|}{c_0^2} \cos(\phi(t)) \\ &\simeq \frac{2(7.4 \text{ km/s})(370 \text{ km/s} + 30 \text{ km/s})}{(3 \times 10^5 \text{ km/s})^2} \end{aligned}$$

$$= 5.8 \times 10^{-8}$$



Estimate

$$\frac{\delta_v c(v)}{c_0} = (\beta - \alpha - 1) \cdot \frac{\delta(\vec{v}^2)}{c_0^2}$$

with 1×10^{-16} clock stability @ orbit time

Measure

e.g. 90 min (instead of 1 day=1440 min on Earth \Rightarrow factor 4 gained)

integration in 5000 orbits

for 2 yrs \rightarrow 50% duty cycle \Rightarrow

$$1.4 \times 10^{-18}$$

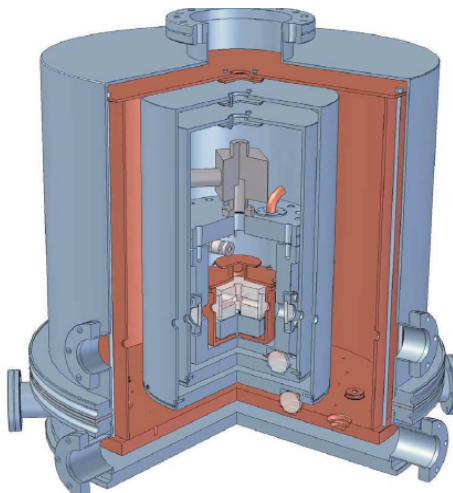
Source: C. Braxmaier



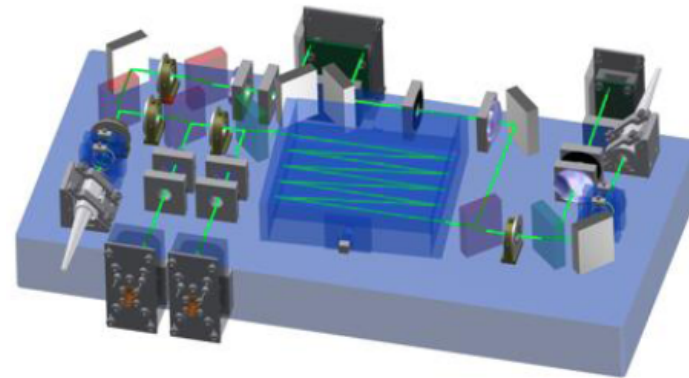
BOOST (BOOst Symmetry Test): Technology Reqmts

→ Payload design in DLR compact satellite bus feasible!

Cavity Reference
 10^{-16} @ 2700s
@ 1016nm



Molecular Clock Reference
 10^{-16} @ 2700s @ 508nm

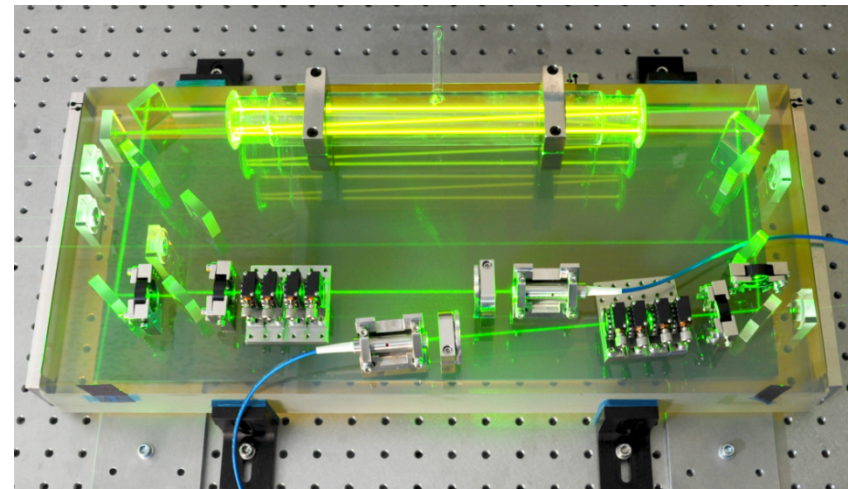


Iodine Setup: EM (35cm x 18 cm)



Status: Iodine standard

- Compact setup: 25cm x 55cm x 10cm
- 30cm long iodine cell in triple pass configuration
- Use of specific AI technology
- MTS @ 532nm
- Modulation either using fiber-EOM or AOM
- $< 3 \times 10^{-15}$ @ 1000s



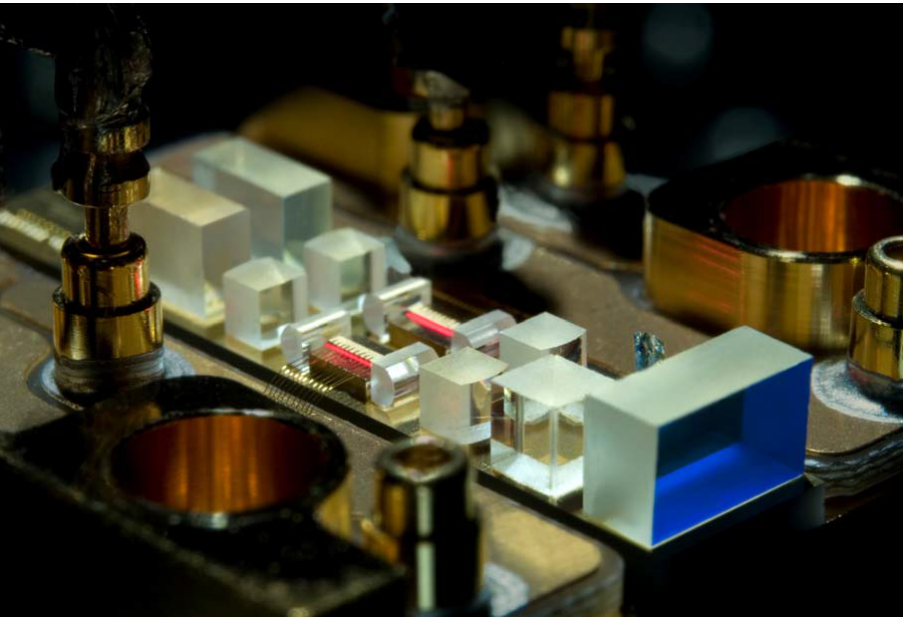
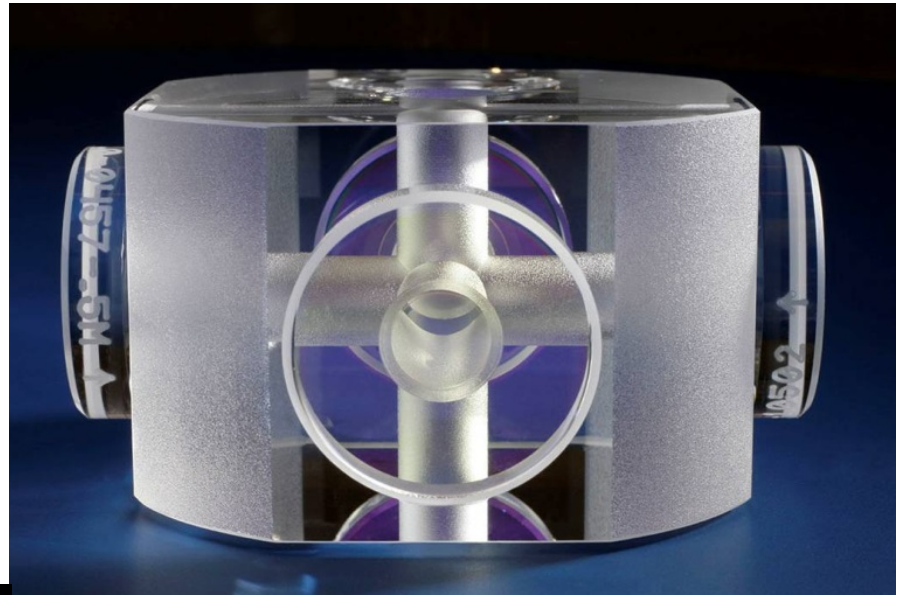
- > MTS @ 508 nm \rightarrow 1/10 of line width compared to 532 nm
- > Expected performance for clock instability:
 $< 1 \times 10^{-16}$ @ 2700 s

Source: C. Braxmaier



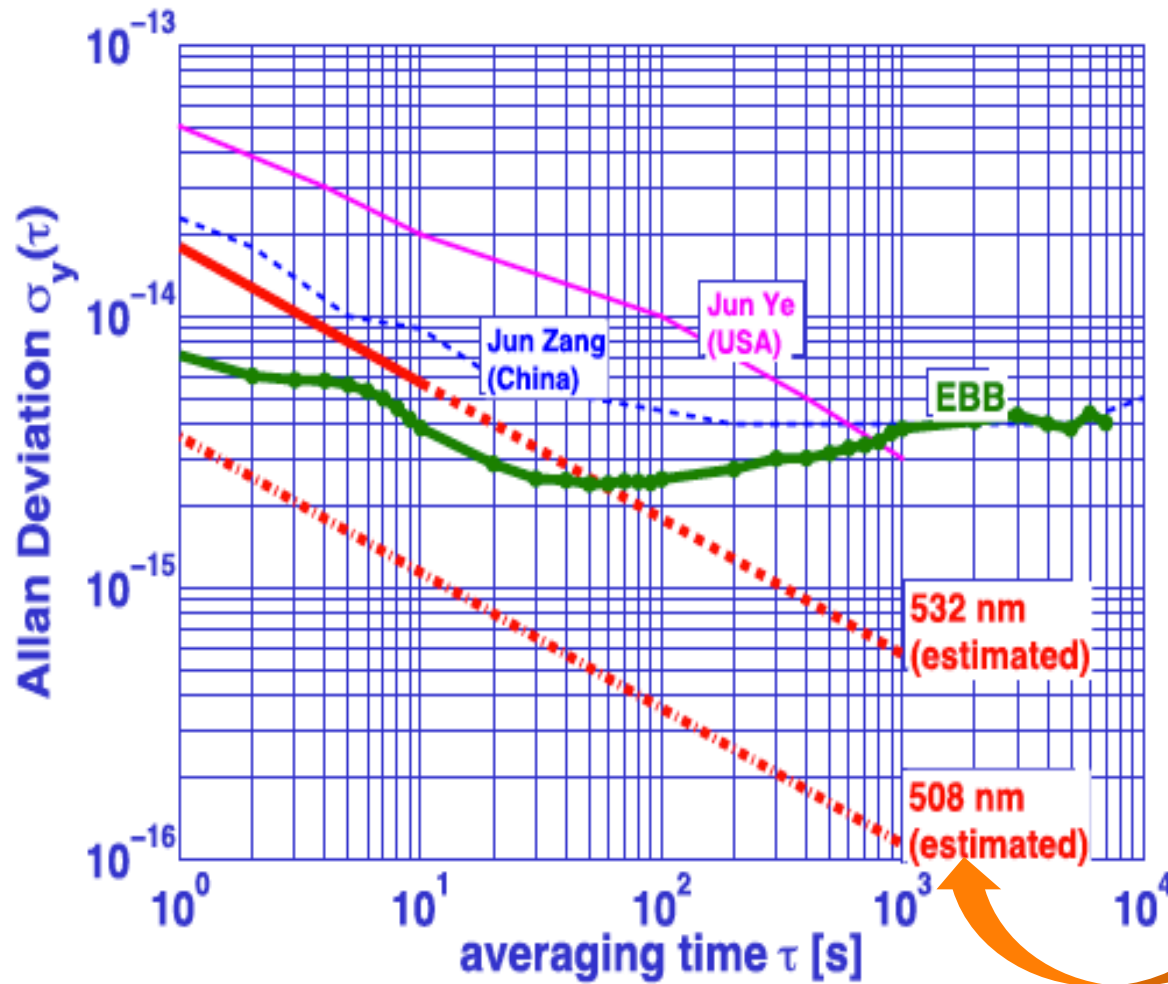
Cavities

- Made from ULE or FS or Zerodur
- 1064nm JPL GRACE FO cavity
 - $5 \cdot 10^{-14}$ @ 1000s
 - TRL 5
- 1064nm SODERN Cavity
 - 10^{-15} @ 100s
 - TRL4-5



Source: C. Braxmaier





Proposed Performance



But that's not all:



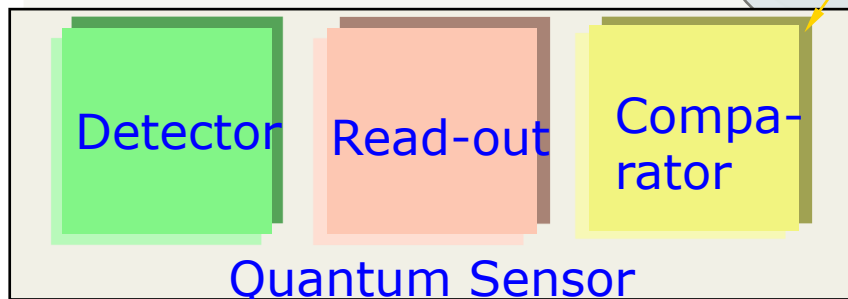
Quantum sensors

Based on:

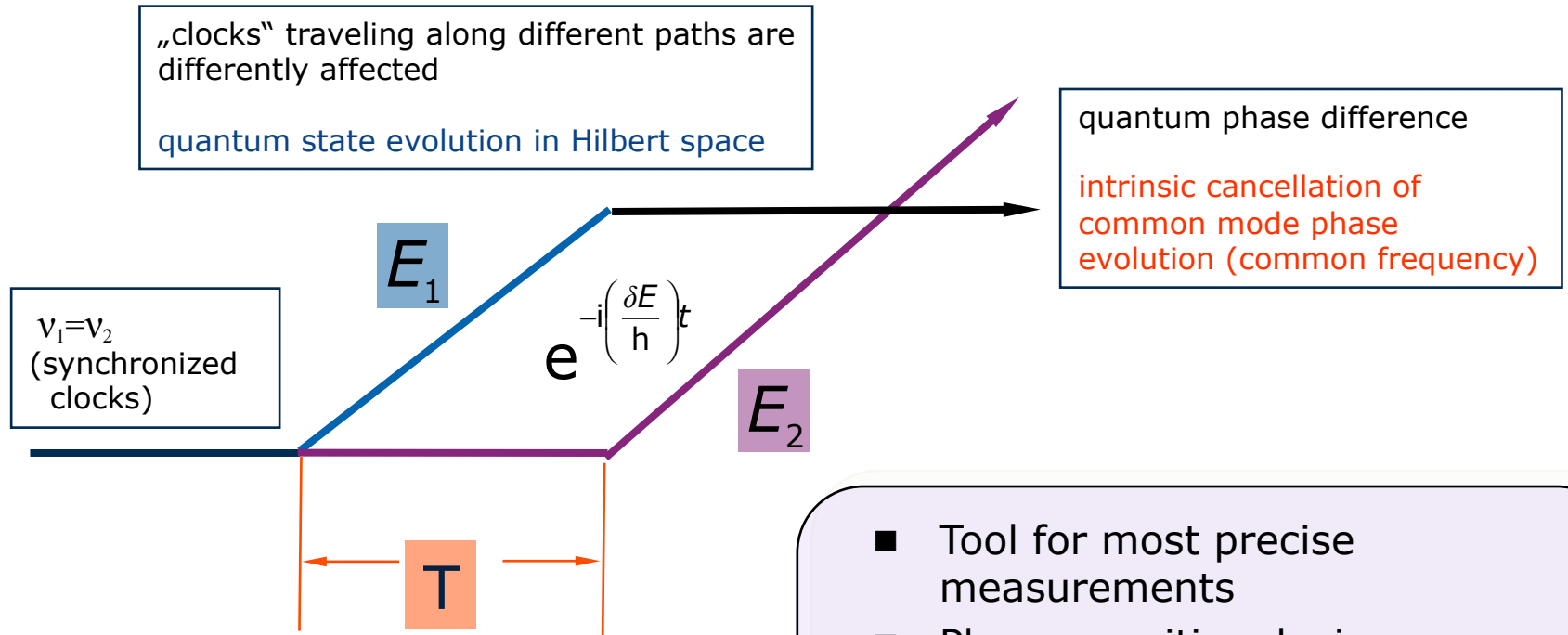
- (1) Ultra-precise optical metrology
 $\delta\nu/\nu < 10^{-17}$ in the optical frequency domain
- (2) Phase-sensitive atom interferometry
 $\delta E/E < 10^{-19}$
due to the sub-microscopic quantum mechanical structure

Needs experimental competence in:

- (1) Processing ultra-cold atomic ensembles:
 - „classical“ laser cooled ensembles: $\sim 1 \mu\text{K}$
 - Bose-Einstein Condensates (BEC): $< 50 \text{ nK}$
 - ultra-cold molecules
- (2) Measuring the phase highly precise:
 - highly stable, phase-locked EM-oscillators (RF-, THz-, optical)
- (3) Calibrating oscillators:
 - frequency comb



Atom Interferometer



■ Optimized for:

- Long interrogation time T
- Narrow atom velocity distribution
- Maximized grav. potential differences
- Minimized external disturbances (em-fields, acoustic noise, seismic noise, thermal gradients)

- Tool for most precise measurements
- Phase-sensitive device
- Sensitivity scales with higher orders of T
- Intrinsic measurement of differential frequencies



Atom Interferometers in Space

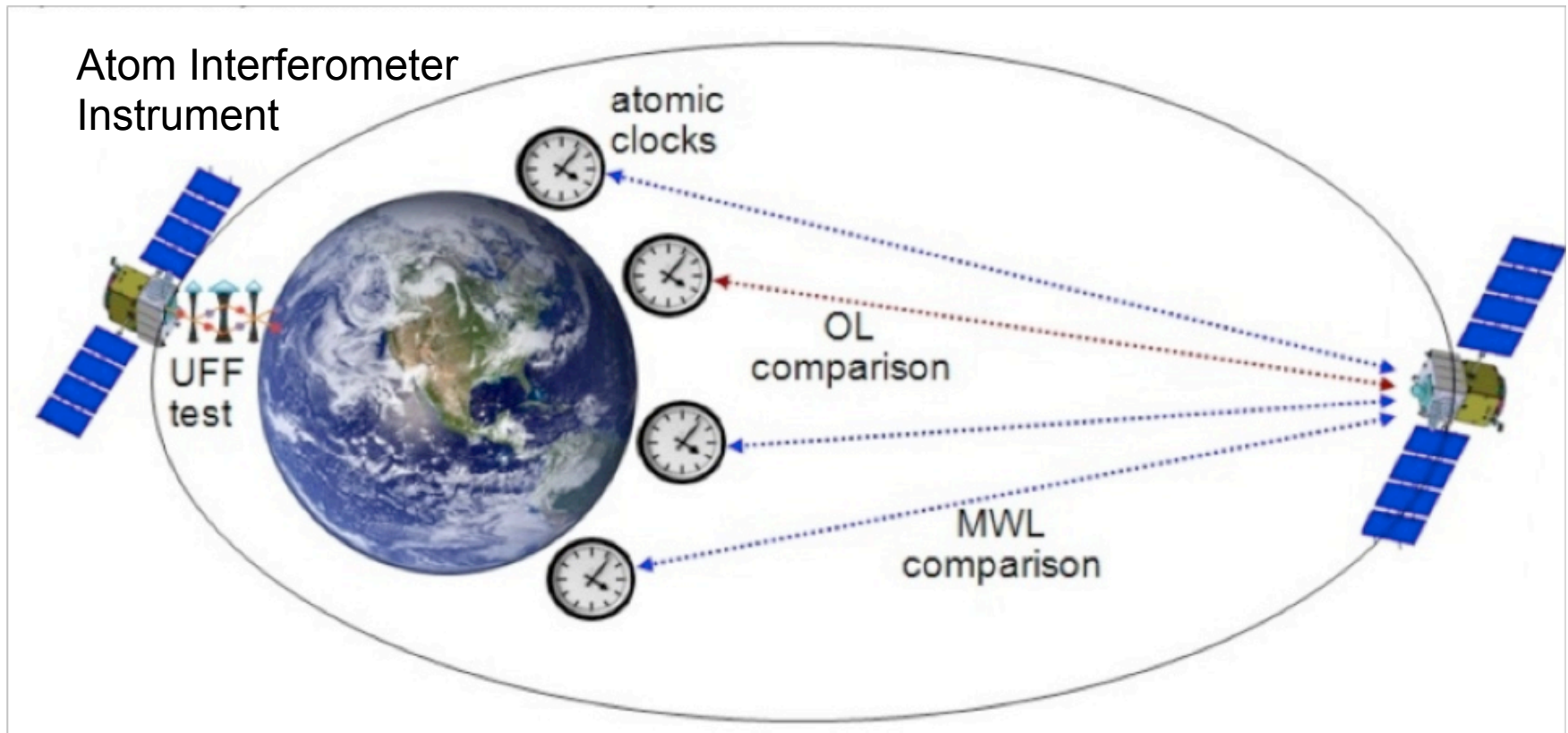
- Highest sensitivity of atom interferometers can be obtained under conditions of weightlessness

- Interrogation time T can be maximized (> 10 s)
- Sensitivity ($\delta\phi$) is proportional to T^2 or T^3 (For comparison: δv of atomic fountain clocks scales with T only.)
- Compensation of gravity allows to reduce atom temperature
- Reduces atom velocity (< 10 cm/s)
- Ultra-cold temperatures enable large atomic ensemble sizes (> 1 cm)
- Further improvement by using degenerated quantum gases (BECs) as sources

- Reduction of disturbances of different noise sources
- Dominant sources like seismicity and acoustic noise can be nearly completely depressed under weightlessness

STE-QUEST (SpaceTime Explorer – Quantum Equivalence Space Test)

- Testing the foundations of General Relativity and measuring



GR / Einstein Equivalence Principle

Universality of
Free Fall

Local Position
Invariance

Local Lorentz
Invariance

